

# Extended Top-down Tree Transducers

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# Motivating samples (GOOGLE TRANSLATE)

## Example (Input in English)

Holly picks flowers to tie them around July's neck.

## Translation to German

Stechpalme wählt Blumen aus, um sie um Ansatz Julis zu binden.

*Holly selects flowers to tie them to approach of July. (??)*

## Retranslation to English

Stechpalme selects flowers, in order to bind it around beginning of July.

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# Another Sample

## Example (Input in German plus reference translation)

Man könnte meinen, meine Meinung zählt nicht.  
*One could believe that my opinion does not count.*

## Translation to English

One could not do mine, my opinion counts.

# Another Sample

## Example (Input in German plus reference translation)

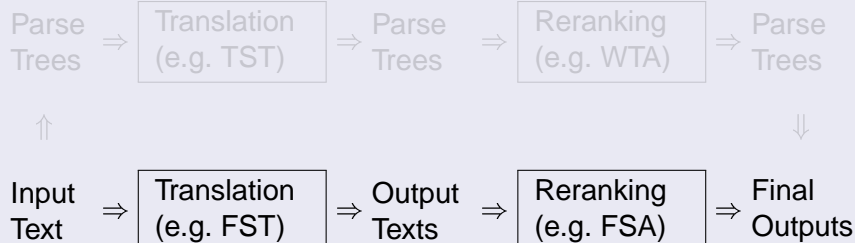
Man könnte meinen, meine Meinung zählt nicht.  
*One could believe that my opinion does not count.*

## Translation to English

One could not do mine, my opinion counts.

# Syntax-based Machine Translation

## Overview

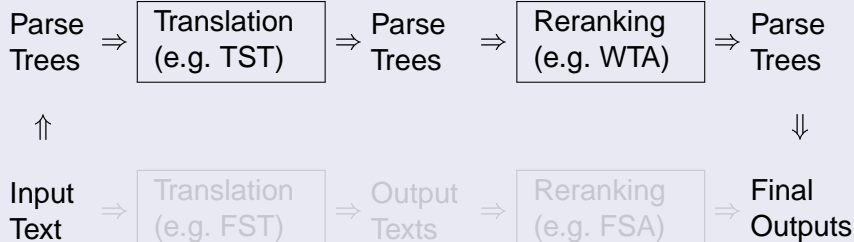


## Abbreviations

- FST = Finite State Transducer
- FSA = Finite State Automaton

# Syntax-based Machine Translation

## Overview

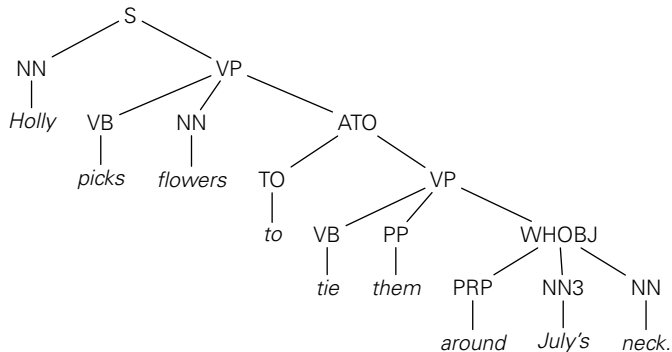


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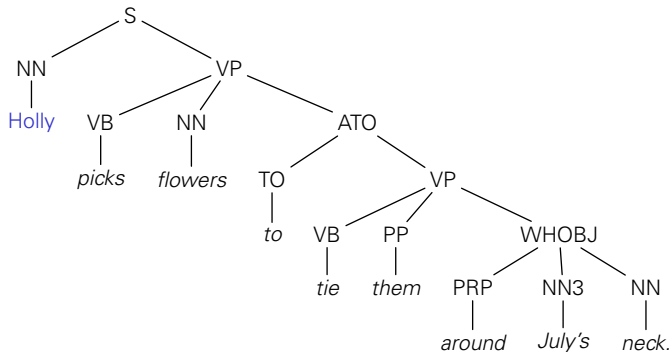
- TST = Tree Series Transducer
- WTA = Weighted Tree Automaton



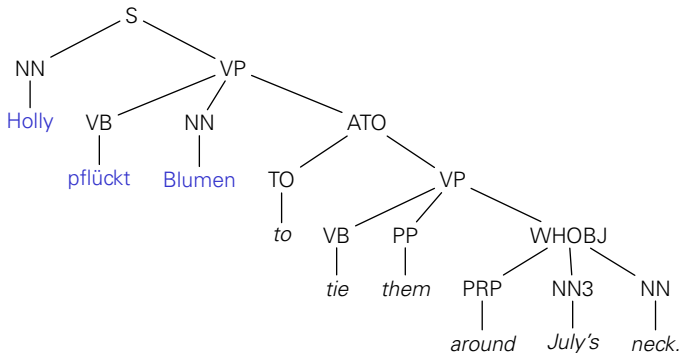
# Syntactic Analysis



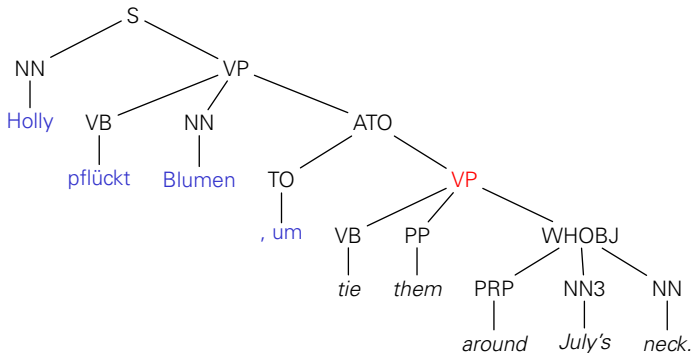
# Syntax-based Machine Translation



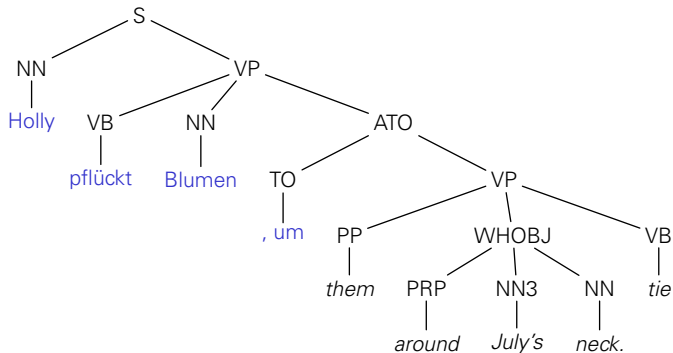
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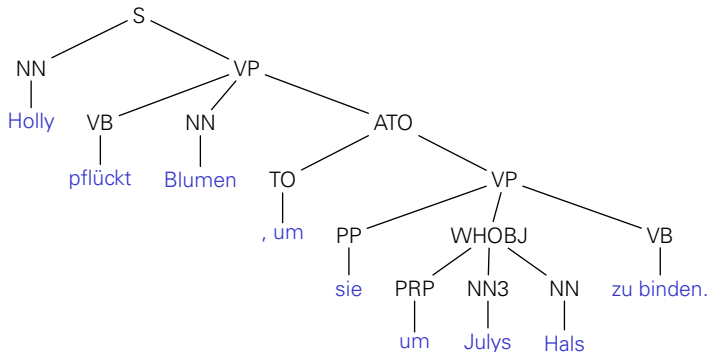
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# Syntax-based Machine Translation



# Why Syntax?

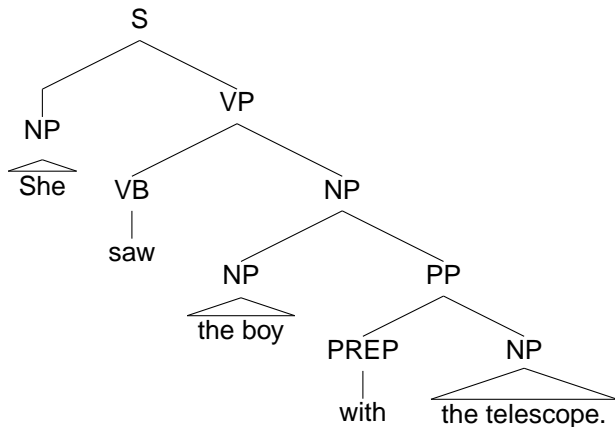
## Example

She saw the boy with the telescope.

# Why Syntax?

## Example

She saw the boy with the telescope.



maybe

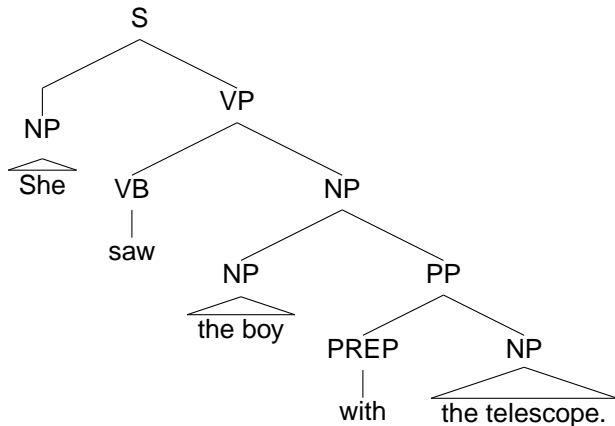


# Why Syntax?

## Example

She saw the boy with the telescope.

0.33

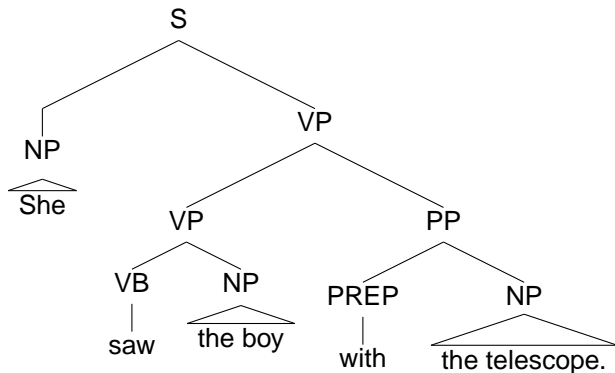


# Why Syntax?

## Example

She saw the boy with the telescope.

more likely

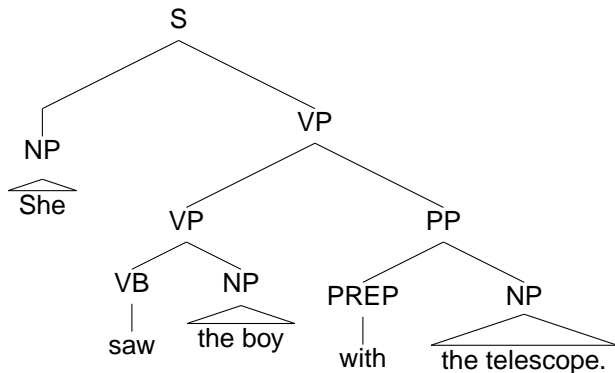


# Why Syntax?

## Example

She saw the boy with the telescope.

0.66



# Why Syntax?

## Example

She saw the boy with the telescope.

## Benefits

- Parsing ambiguities do not affect translation model
- Translation can use syntactic structure

## Remaining problem



VS.



# Translation Model

## Criteria

- (a) Generalize FST; in particular, epsilon-transitions
- (b) Efficient training
- (c) Handles rotation
- (d) Closed under composition

## Existing Models

Model \ Criterion	(a)	(b)	(c)	(d)
Top-down tree transducer	–	x	–	x
Quasi-alphabetic tree bimorphism	–	?	–	x
Synchronous context-free grammar	x	x	–	x
Synchronous tree substitution grammar	x	x	x	–
Synchronous tree adjoining grammar	x	x	x	–

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- 1 Motivation
- 2 Extended Top-down Tree Transducer**
- 3 Expressive Power
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# Syntax

## Definition

$(Q, \Sigma, \Delta, I, R)$  xtt

- $Q$  finite set of **states**
- $\Sigma$  and  $\Delta$  ranked alphabets
- $I \subseteq Q$  **initial states**
- $R$  finite set of **rules** of the form  $q(t) \rightarrow u$  where  $q \in Q$ ,  $t \in T_{\Sigma}(X)$ , and  $u \in T_{\Delta}(Q(\text{var}(t)))$

## References

- Arnold, Dauchet: Bi-transductions de forêts. ICALP 1976
- Graehl, Knight: Training Tree Transducers. HLT-NAACL 2004

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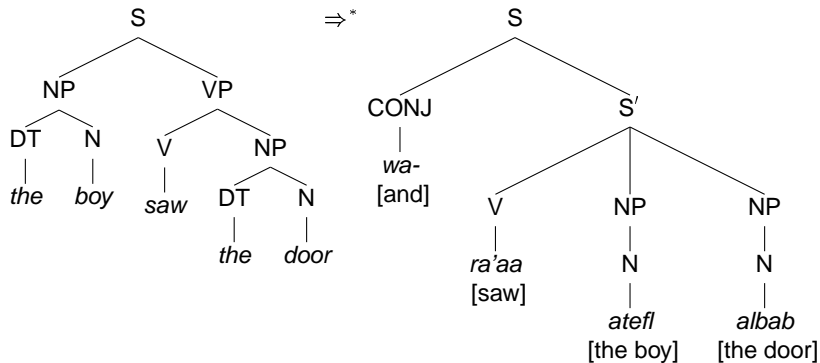
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## Syntax — Example



## Question

How to implement this English  $\rightarrow$  Arabic translation using xtt?

## Syntax — Example (cont'd)

## Example

States  $\{q, q_S, q_V, q_{NP}\}$  of which only  $q$  is initial

$$q(x_1) \rightarrow q_S(x_1) \quad (r_1)$$

$$q(x_1) \rightarrow S(\text{CONJ}(wa-), q_S(x_1)) \quad (r_2)$$

$$q_S(S(x_1, VP(x_2, x_3))) \rightarrow S'(q_V(x_2), q_{NP}(x_1), q_{NP}(x_3)) \quad (r_3)$$

$$q_V(V(saw)) \rightarrow V(ra'aa) \quad (r_4)$$

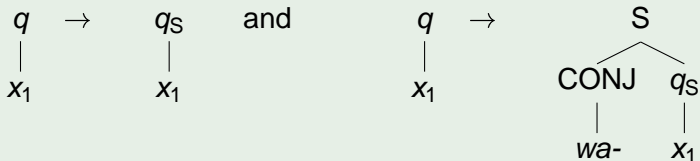
$$q_{NP}(NP(DT(the), N(boy))) \rightarrow NP(N(ateff)) \quad (r_5)$$

$$q_{NP}(NP(DT(the), N(door))) \rightarrow NP(N(albab)) \quad (r_6)$$

## Syntax — Example (cont'd)

## Example

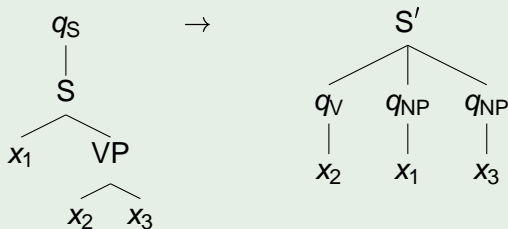
- ① **Nondeterminism** and **epsilon rules** (rules  $r_1$  and  $r_2$ )



## Syntax — Example (cont'd)

## Example

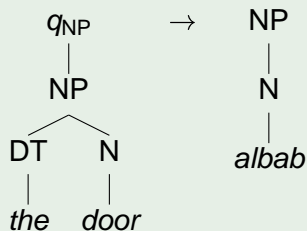
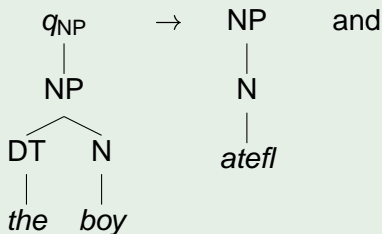
- 1 **Nondeterminism** and **epsilon rules** (rules  $r_1$  and  $r_2$ )
- 2 **Deep** attachment of variables (rule  $r_3$ )



## Syntax — Example (cont'd)

## Example

- 1 **Nondeterminism** and **epsilon rules** (rules  $r_1$  and  $r_2$ )
- 2 **Deep** attachment of variables (rule  $r_3$ )
- 3 **Finite** look-ahead (rules  $r_4$  and  $r_5$ )



# Semantics

$$M = (Q, \Sigma, \Delta, I, R)$$

## Definition

Let  $\xi, \zeta \in T_{\Delta}(Q(T_{\Sigma}))$ . Then  $\xi \Rightarrow_M \zeta$  if there exist

- 1 a rule  $q(t) \rightarrow u$
- 2 a substitution  $\theta: X \rightarrow T_{\Sigma}$
- 3 a position  $w \in \text{pos}(\xi)$

such that  $\xi|_w = q(t\theta)$  and  $\zeta = \xi[u\theta]_w$

## Definition

Computed transformation:

$$\tau_M = \{(t, u) \in T_{\Sigma} \times T_{\Delta} \mid \exists q \in I: q(t) \Rightarrow_M^* u\}$$

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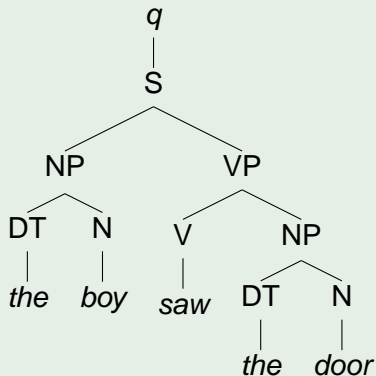
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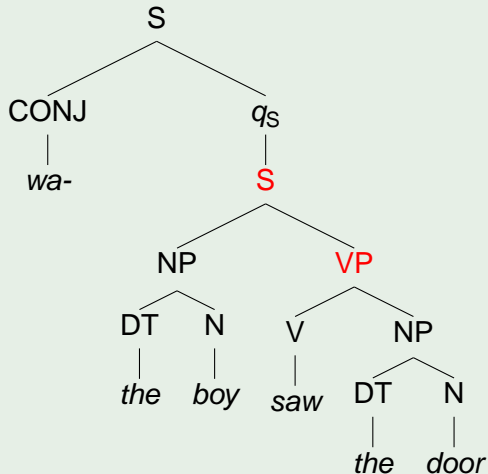
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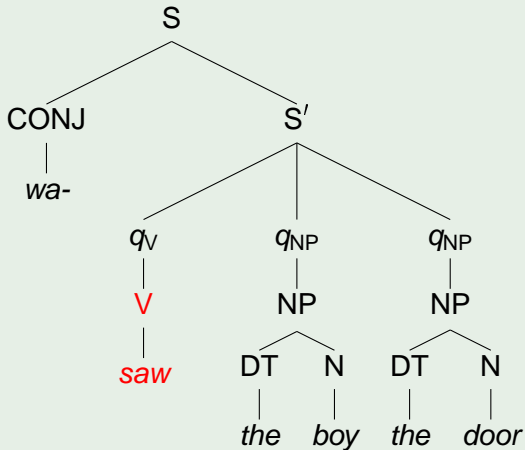
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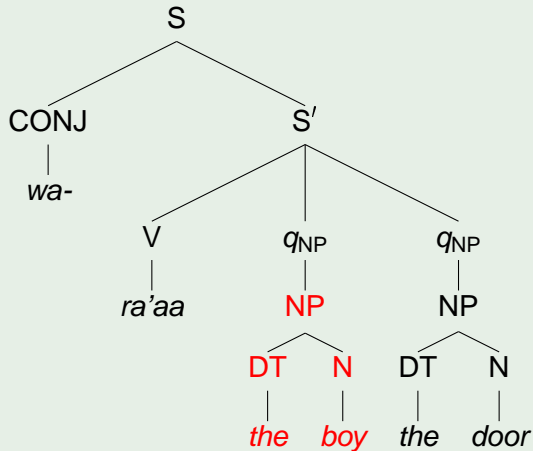
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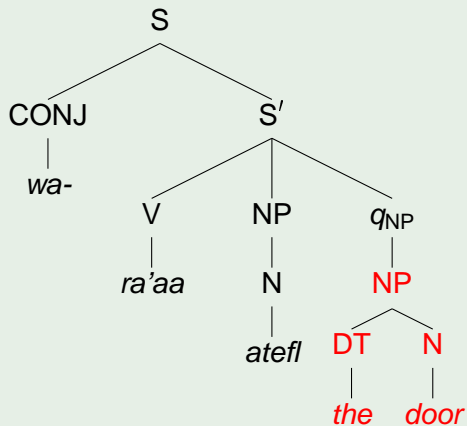
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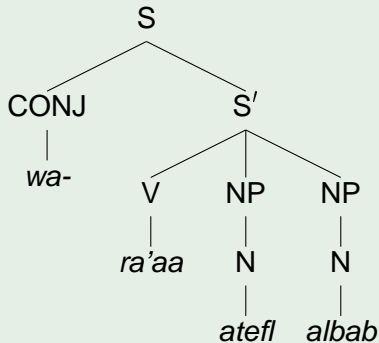
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# Wanted Expressivity

## Criteria

- 1 Generalize FST including epsilon rules (In-tdtt: **no**, In-xtt: **yes**)
- 2 Efficiently trainable (In-tdtt: **yes**, In-xtt: **yes**)
- 3 Can handle rotations (In-tdtt: **no**, In-xtt: **yes**)



- 4 Can handle flattenings (In-tdtt: **no**, In-xtt: **yes**)



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# Wanted Expressivity (Cont'd)

## Criteria

- 1 Preservation of Recognizability (In-tdtt: **yes**, In-xtt: **yes**)
- 2 Closure under composition (In-tdtt: **yes**, In-xtt: **no**)

## Definition

- **linear**: no right-hand side contains a duplicate variable
- **non-deleting**: all right-hand sides contain all variables of their left-hand side
- **epsilon-free**: no rules of the form  $q(x) \rightarrow u$

# Wanted Expressivity (Cont'd)

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## Discriminative features

- **Finite** look-ahead
- **Epsilon** rules
- **Deep** attachment of variables

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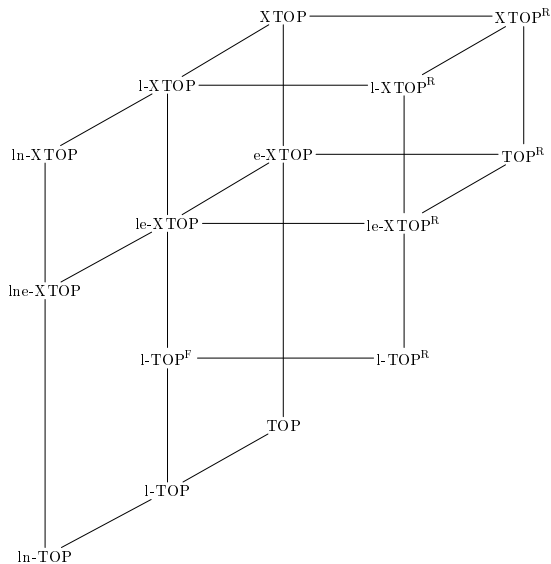
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# Hasse Diagram





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# Closure under Composition

## Theorem

*Every  $1\text{-TOP} \subseteq \mathcal{L} \subseteq \text{XTOP}$  is not closed under composition.*

## Proof.

Composition closure of  $1\text{-TOP}$  is  $1\text{-TOP}^R$ . By the diagram,  $1\text{-TOP}^R \not\subseteq \text{XTOP}$ . □

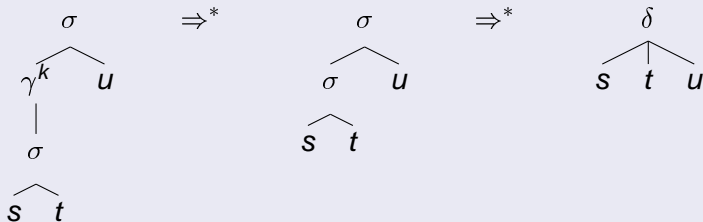
# Closure under Composition (Cont'd)

## Theorem

Every  $\text{In-TOP} \subseteq \mathcal{L} \subseteq \text{1-XTOP}^R$  that contains rotations or flattenings is not closed under composition.

## Proof.

Prove  $\text{In-TOP} ; \{\tau_{\text{flat}}\} \not\subseteq \text{1-XTOP}^R$  using, e.g.,



# Closure under Composition (Cont'd)

## Theorem

$XTOP^R$  is not closed under composition.

## Proof.

Follow classical proof for  $TOP^R$ . □

## Conclusion or Bad news

No (mentioned) class of xtt computes a closed class of transformation.

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# Compositions

## Problem

Compositions are extremely important (e.g., for a framework)!

## Questions

- 1 Identify a suitable subclasses that is closed under composition (expressive vs. closure)
- 2 Determine whether two given l-xtt can be composed
- 3 What is the composition closure of l-xtt
- 4 Identify superclasses that are closed under composition and still preserve recognizability (preservation vs. closure)
- 5 What is the effect of epsilon rules on composition closure

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# Tiburon

## Features

- Implements xtt (and tree automata; everything also weighted)
- Framework with command-line interface
- Optimized for machine translation

## Algorithms

- Application of xtt to input tree
- Application of xtt to input language
- Backward application of xtt to output language
- Composition (for some xtt)
- ...



# Example in Tiburon

## Example

```

q
q.x0:                -> qS.x0
q.x0:                -> S(CONJ(wa-) qS.x0)
qS.S(x0: VP(x1: x2:)) -> S'(qV.x1 qNP.x0 qNP.x2)
qV.V(saw)           -> V(ra'aa)
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```

# References

- Arnold, Dauchet: Bi-transductions de forêts. ICALP 1976
- Baker: Composition of top-down and bottom-up tree transducers. *Inform. Control* 41. 1979
- Engelfriet: Bottom-up and top-down tree transformations—a comparison. *Math. Syst. Theory* 9. 1975
- Engelfriet: Top-down tree transducers with regular look-ahead. *Math. Syst. Theory* 10. 1976
- May, Knight: Tiburon: A Weighted Tree Automata Toolkit. CIAA 2006
- M., Graehl, Hopkins, Knight: The power of extended top-down tree transducers. 2008

Thank You for your attention!