

# Extended Multi Bottom-up Tree Transducers

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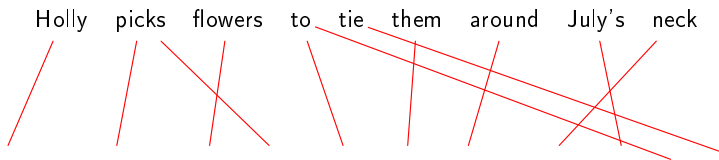
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Kyoto — September 16, 2008

# Classic Approach (simplified)

Source: Google Translate

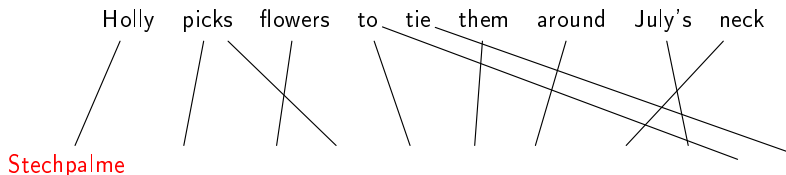


## Steps

- 1 Select scheme
- 2 Translate words individually
- 3 Rescore using word sequences (bigrams, trigrams, etc.)

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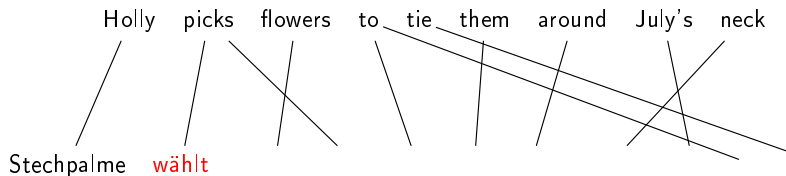


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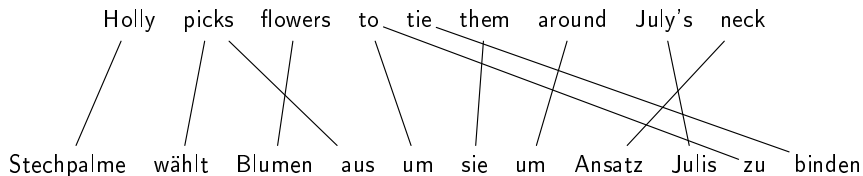


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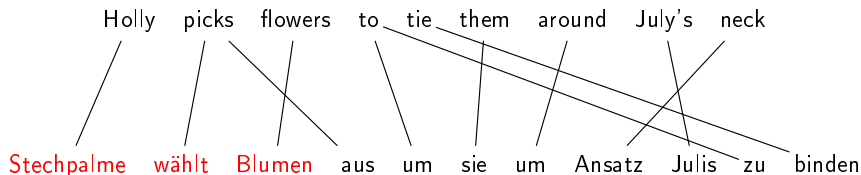


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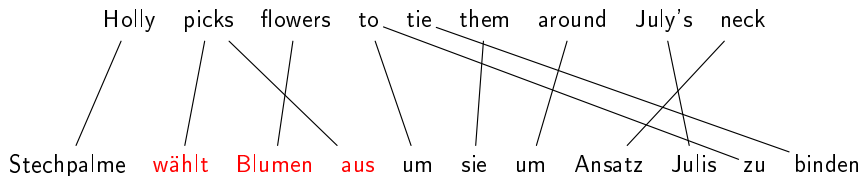


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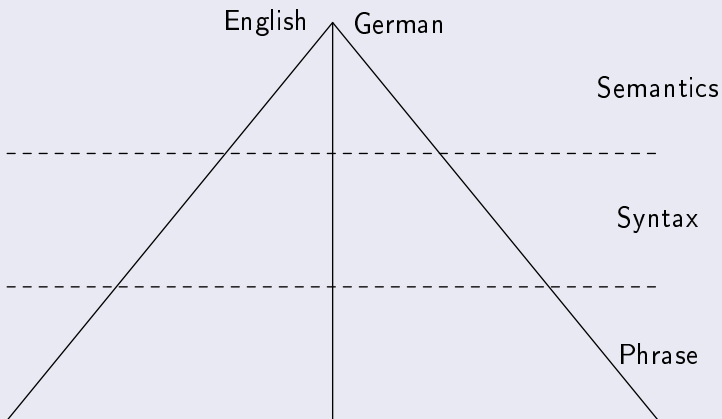


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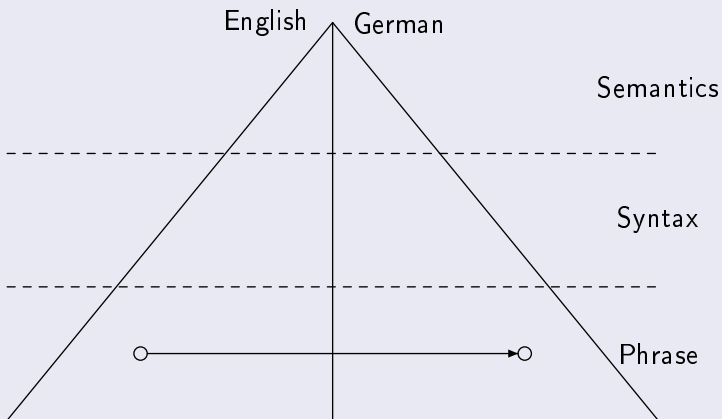
## Overview





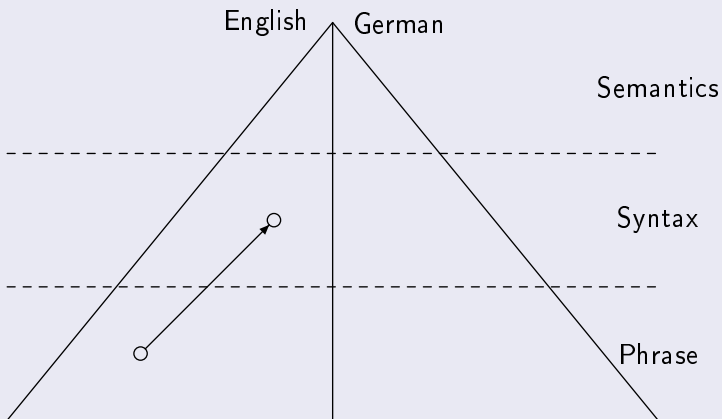
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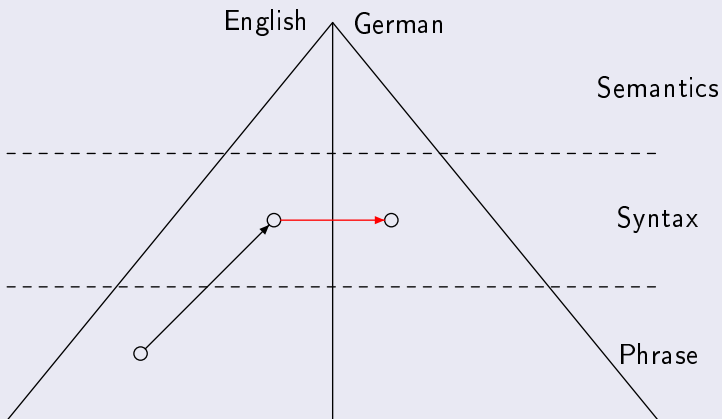
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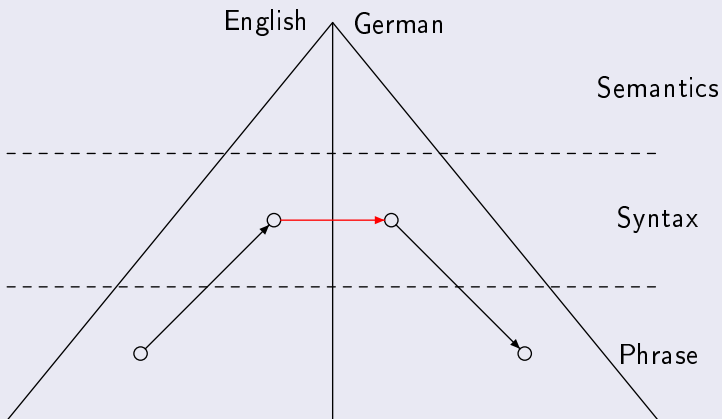
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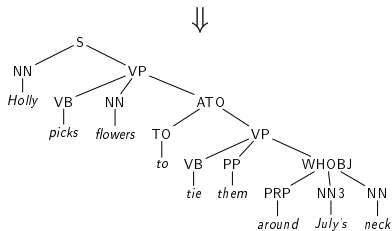
## Syntax-based Approach (cont'd)

Holly picks flowers to tie them around July's neck



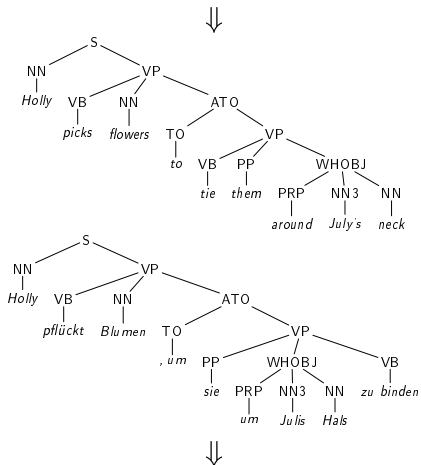
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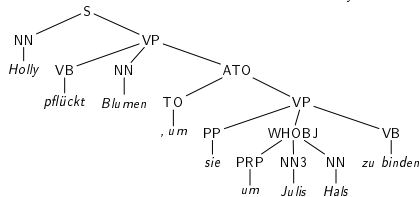
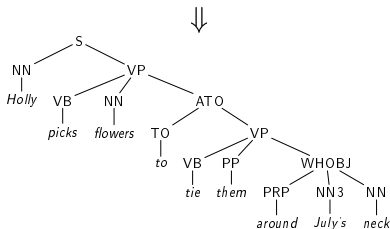
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# Syntax-based Approach (cont'd)

Holly picks flowers to tie them around July's neck



⇓

Holly pflückt Blumen, um sie um Julis Hals zu binden



## Reasonable formal models (ala Knight)

### Required properties

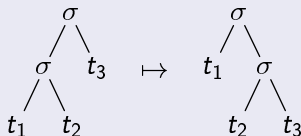
- (a) generalize finite-state transducers (the string case)
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## Example rotation



# Models of tree transformations

## Overview

Model \ Criterion	(a)	(b)	(c)	(d)
Linear nondeleting top-down tt				
Quasi-alphabetic tree bimorphism		?		
Synchronous context-free grammar				
Synchronous tree substitution grammar				
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Linear complete tree bimorphism				
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- 2 Extended multi bottom-up tree transducer
- 3 Theoretical results



# Syntax

## Definition

**eXtended Multi Bottom-Up Tree Transducer**  $(Q, \Sigma, \Delta, F, R)$

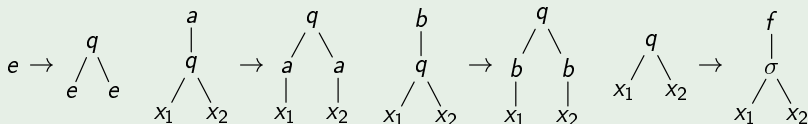
- $Q$  ranked alphabet of *states*
- $\Sigma$  and  $\Delta$  ranked alphabets of input and output symbols
- $F \subseteq Q$  final states (non-zero ranked)
- $R$  finite set of (rewrite) rules  $l \rightarrow r$  with  $l \in T_{\Sigma}(Q(X))$  and  $r \in Q(T_{\Delta}(X))$

# A full example

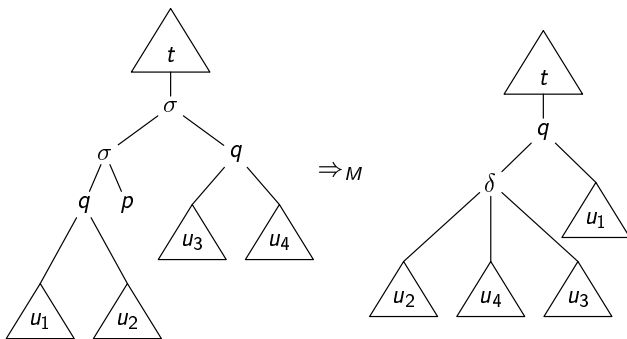
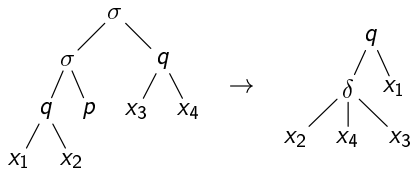
## Example

xmbutt  $(Q, \Sigma, \Delta, F, R)$  with

- $Q = \{f, q\}$
- $\Sigma = \{a^{(1)}, b^{(1)}, e^{(0)}\}$  and  $\Delta = \Sigma \cup \{\sigma^{(2)}\}$
- $F = \{f\}$
- the following rules in  $R$

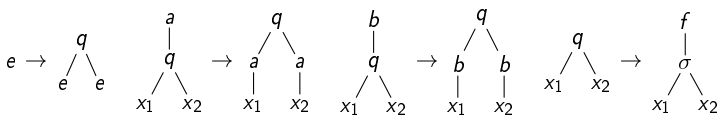


## Semantics





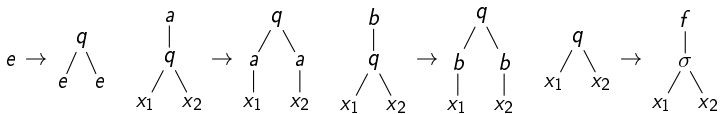
# A full example (cont'd)



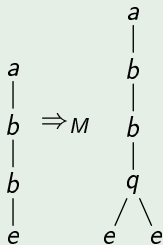
## Example

$a$   
 $|$   
 $b$   
 $|$   
 $b$   
 $|$   
 $e$

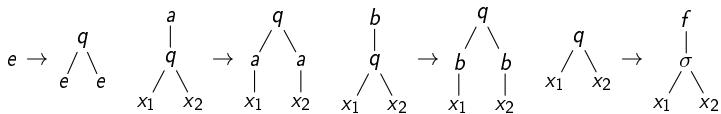
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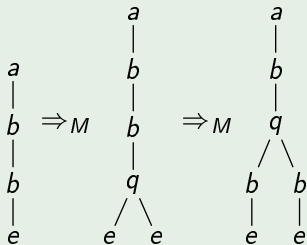
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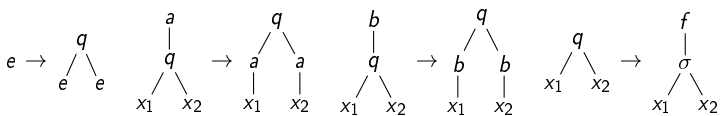
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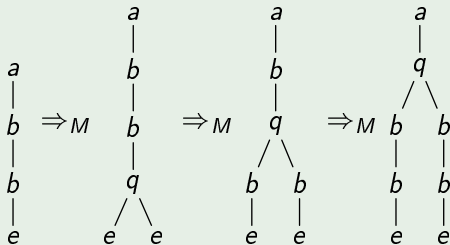
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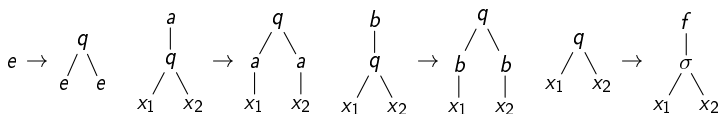
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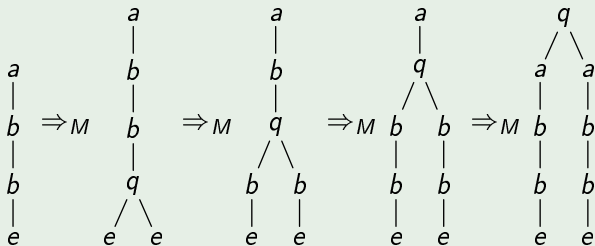
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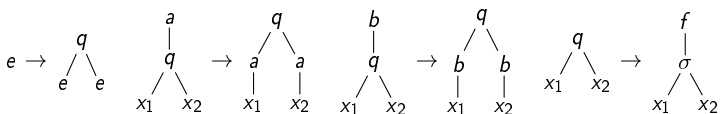
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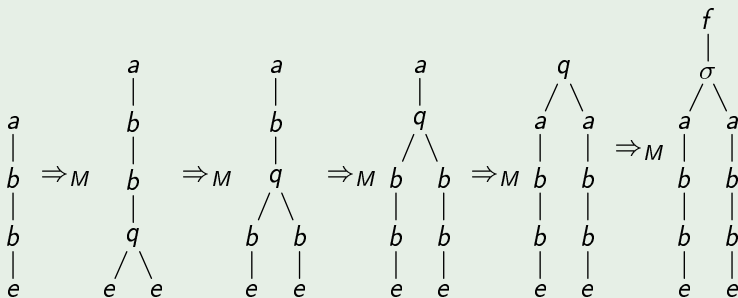
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## A full example (cont'd)



## Example



# Semantics (cont'd)

## Definition

$M = (Q, \Sigma, \Delta, F, R)$  xmbutt

$$\tau_M = \{(t, u) \mid \exists q \in F: t \Rightarrow_M^* q(u, \dots)\}$$

## Example

Our example xmbutt  $M$  computes:

$$\tau_M = \{(t, \sigma(t, t)) \mid t \in T_\Sigma\}$$

**Note** that the image is not recognizable.

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# Syntactical restrictions

## Definition

$\text{xmbutt} (Q, \Sigma, \Delta, F, R)$  is

- **linear** if every right-hand side (of a rule) does not contain duplicate variables
- **nondeleting**, if every right-hand side contains all variables of its left-hand side

## Example

Our example  $\text{xmbutt}$  is linear and nondeleting.

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# Generalization of the string case

## Theorem

*Every fst (including epsilon-rules) can be simulated by an xmbutt.*

## Property summary

- (a) generalize finite-state transducers (the string case)
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*For every (linear)  $xmbutt$  there exists an equivalent (linear) nondeleting  $xmbutt$ .*

## Proof.

Nondeterministically guess which subtrees will be deleted and process those in nullary states. □

## Note

Nullary states act like look-ahead.

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## Theorem (Decomposition)

*Every (linear) xmbutt can be simulated by a composition of a linear and nondeleting extended top-down tree transducer and a deterministic (single-use) top-down tree transducer.*

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# Rotations

## Theorem

*Every linear extended top-down tree transducer can be simulated by a linear xmbutt.*

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Similar as the proof for the non-extended case.

## Corollary

Xmbutt can handle rotations.

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# One-symbol normal form

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$xmbutt (Q, \Sigma, \Delta, F, R)$  in **one-symbol normal form** if exactly one input or output symbol occurs in each rule.

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*For every (linear, nondeleting)  $xmbutt$  there exists an equivalent (linear, nondeleting)  $xmbutt$  in one-symbol normal form.*



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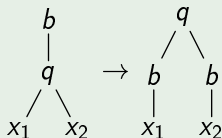
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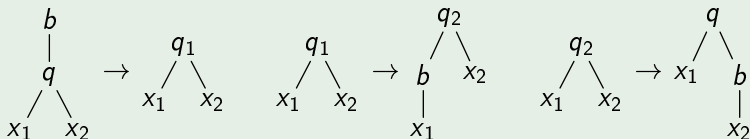
# One-symbol normal form (cont'd)

## Example

Rule not in one-symbol normal form:



Replacement rules for this rule:



# Composition construction

## Definition

from xmbutt  $M = (Q, \Sigma, \Gamma, F, R)$  and  $N = (Q', \Gamma, \Delta, G, P)$   
construct

$$M ; N = (Q \langle Q' \rangle, \Sigma, \Delta, F \langle G \rangle, R')$$

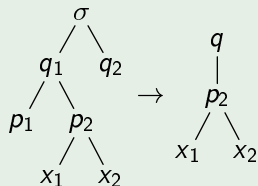
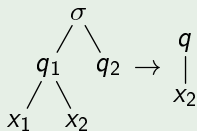
with three types of rules:

- 1 input-consuming rules constructed from input-consuming rules of  $R$
- 2 epsilon rules constructed from epsilon-rules of  $P$
- 3 epsilon rules constructed from an epsilon rule of  $R$  followed by an input consuming rule of  $P$

# Composition construction (cont'd)

## Example

Input consuming rule of  $R$  and resulting rule:

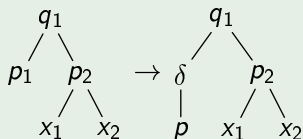


# Composition construction (cont'd)

## Example

Epsilon rule of  $P$  and resulting rule:

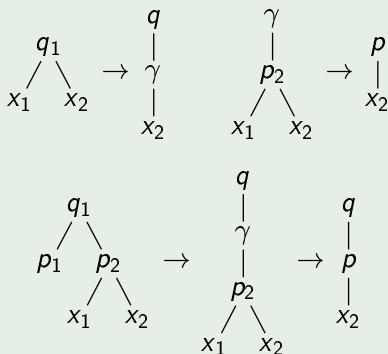
$$p_1 \rightarrow \begin{array}{c} \delta \\ | \\ p \end{array}$$



## Composition construction (cont'd)

## Example

Epsilon rule of  $R$  and input consuming of  $P$  and resulting rule:



# Closure under composition

## Theorem

*For every linear xmbutt  $M$  and xmbutt  $N$ , there exists an xmbutt that computes the composition of the transformations computed by  $M$  and  $N$ .*

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The class of transformations computed by linear xmbutt is closed under composition.

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generalize finite-state transducers (the string case)

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able to handle rotations

class of transformations closed under composition



## References

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- [Gécseg](#), [Steinby](#): *Tree Automata*. Akadémiai Kiadó, Budapest 1984

Thank you for your attention!

