

Minimizing Weighted Tree Grammars using Simulation

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Simulations

- “Half” a bisimulation
- Used in (lossless) reductions of the size of grammars
- Also used in logic (inseparability by logic formulae)

Rough definition

A nonterminal B **simulates** another nonterminal A if any rule involving A is covered by a rule involving B

But

our new definition is not as intuitive

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<i>Property</i>	<i>Existing Simulation</i>	
	Backward	Forward
Generalization		
unweighted simulation	✓	✓
weighted bisimulation	x	x
Computation		
Admits greatest simulation	✓	✓
Yields minimal device	x	x
Easy to compute	✓	✓

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Tree Series

- Assigns **weight** (e.g. a probability) to each tree
- Weights drawn from semiring; e.g. $([0, 1], \max, \cdot, 0, 1)$

Weighted Tree Grammar

- **Finite** representation of a tree series

Applications

- Re-ranker implementing a language model
- Representation of a parser (or parses)

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Definition

Weighted tree grammar (WTG) is tuple $(N, \Sigma, \mathcal{S}, S, P)$ where

- N : finite set of *nonterminals*
- Σ : ranked alphabet of *symbols*
- $\mathcal{S} = (\mathcal{S}, +, \cdot, 0, 1)$: semiring of *weights*
- $S \in N$: *start nonterminal*
- P finite set of productions of the form $A \xrightarrow{s} \sigma(A_1, \dots, A_k)$ with $A, A_1, \dots, A_k \in N$, $s \in \mathcal{S}$, and $\sigma \in \Sigma_k$

Notation

We write $\text{wt}(A \rightarrow \sigma(A_1, \dots, A_k)) = s$ if $A \xrightarrow{s} \sigma(A_1, \dots, A_k) \in P$

Definition

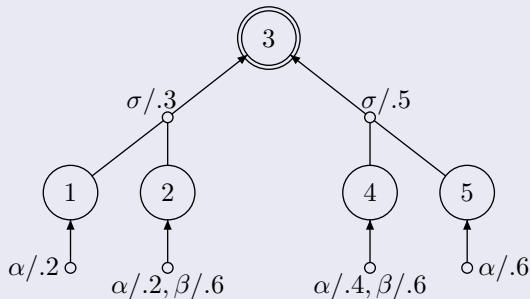
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Sample Grammar



Restriction

Here only for idempotent (i.e. $1 + 1 = 1$) semirings

Definition

Let $c \in C_{\Sigma}(N)$ and $p = A \xrightarrow{S} \sigma(A_1, \dots, A_k) \in P$

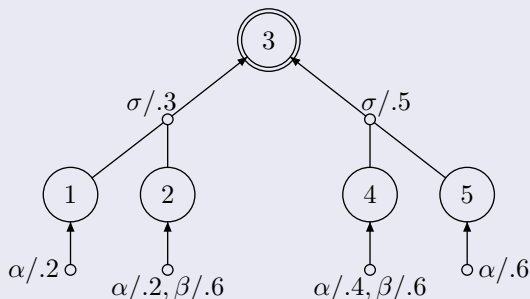
$$c[A] \stackrel{p}{\Rightarrow} c[\sigma(A_1, \dots, A_k)]$$

Weight of a tree $t \in T_{\Sigma}$ in nonterminal A :

$$\text{wt}(t, A) = \sum_{\substack{p_1, \dots, p_n \in P \\ A \xrightarrow{p_1} \dots \xrightarrow{p_n} t}} \text{wt}(p_1) \cdot \dots \cdot \text{wt}(p_n)$$

Weight of t : $\text{wt}(t) = \text{wt}(t, S)$

Sample Grammar



Sample derivations for input tree: $\sigma(\alpha, \alpha)$

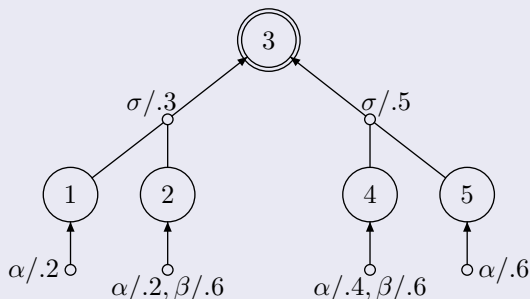
$3 \Rightarrow_G \sigma(1, 2) \Rightarrow_G \sigma(\alpha, 2) \Rightarrow_G \sigma(\alpha, \alpha)$

rule weights: $0.3 \cdot 0.2 \cdot 0.2$

$3 \Rightarrow_G \sigma(4, 5) \Rightarrow_G \sigma(\alpha, 5) \Rightarrow_G \sigma(\alpha, \alpha)$

rule weights: $0.5 \cdot 0.4 \cdot 0.6$

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A quasi-order $\preceq \subseteq N^2$ is a **backward simulation** if for every $A \preceq B$, $\sigma \in \Sigma_k$, and $A_1, \dots, A_k \in N$ there exist $A_1 \preceq B_1, \dots, A_k \preceq B_k$ such that

$$\text{wt}(A \rightarrow \sigma(A_1, \dots, A_k)) \sqsubseteq \text{wt}(B \rightarrow \sigma(B_1, \dots, B_k))$$

New definition

A quasi-order $\preceq \subseteq N^2$ is a **backward simulation** if for every $A \preceq B$, $\sigma \in \Sigma_k$, and $A_1, \dots, A_k \in N$

$$\sum_{\substack{B_1 \in \uparrow A_1 \\ \vdots \\ B_k \in \uparrow A_k}} \text{wt}(A \rightarrow \sigma(B_1, \dots, B_k)) \sqsubseteq \sum_{\substack{B_1 \in \uparrow A_1 \\ \vdots \\ B_k \in \uparrow A_k}} \text{wt}(B \rightarrow \sigma(B_1, \dots, B_k))$$

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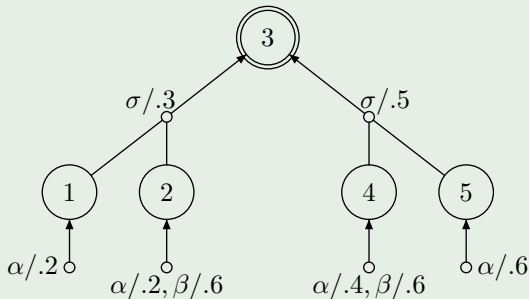
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An example

Example



$1 \preceq 2 \preceq 4$ and $1 \preceq 5$

Theorem

There exists a greatest backward simulation for G .

Lemma (Main lemma)

For every $t \in T_\Sigma$ and $A \preceq B$

$$\text{wt}(t, A) \sqsubseteq \text{wt}(t, B)$$

Corollary

For every $t \in T_\Sigma$ and $A \preceq B \preceq A$

$$\text{wt}(t, A) = \text{wt}(t, B)$$

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Reducing the grammar

Definition

Let $\simeq = \preceq \cap \succeq^{-1}$. Let $(G/\simeq) = (N', \Sigma, S, S', P')$ with

- $N' = (N/\simeq)$
- $S' = [S]$
- for every $\sigma \in \Sigma_k$ and $A', A'_1, \dots, A'_k \in N'$

$$\text{wt}(A' \rightarrow \sigma(A'_1, \dots, A'_k)) = \sum_{A_1 \in A'_1, \dots, A_k \in A'_k} \text{wt}(A \rightarrow \sigma(A_1, \dots, A_k))$$

with $A \in A'$

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G and (G/\simeq) are equivalent.

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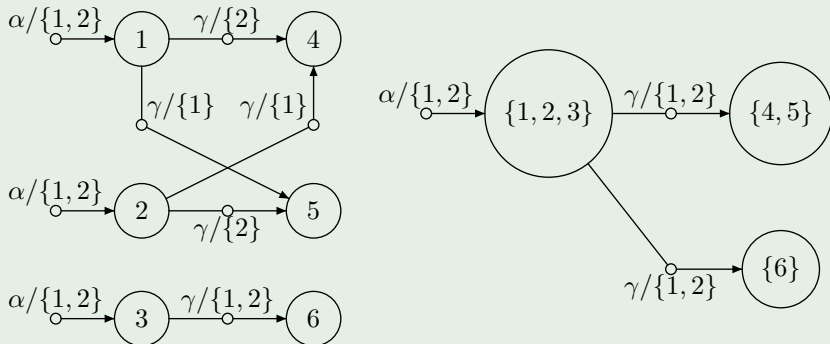
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Semiring $(\mathcal{P}(\{1, 2\}), \cup, \cap, \emptyset, \{1, 2\})$

Example (Old backward simulation)

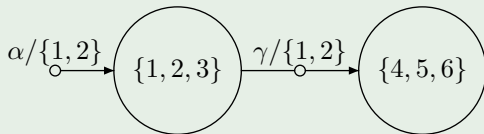
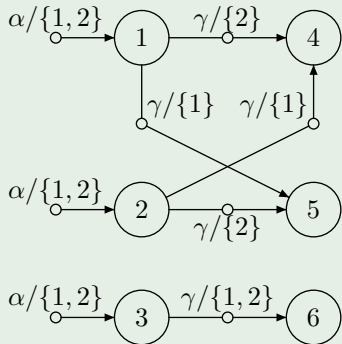


$1 \preceq 2 \preceq 3 \preceq 1$ and $4 \preceq 5 \preceq 4 \preceq 6$, but $6 \not\preceq 4$

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$1 \preceq 2 \preceq 3 \preceq 1$ and $4 \preceq 5 \preceq 6 \preceq 4$

Algorithm computing the greatest simulation

$R_0 \leftarrow N \times N$

$i \leftarrow 0$

repeat

$j \leftarrow i$

for all $\sigma \in \Sigma_k$ and $A_1, \dots, A_k \in N$ **do**

$R_{i+1} \leftarrow \{(A, B) \in R_i \mid$

$$\sum_{\substack{B_1 \in \uparrow_{R_i} A_1 \\ \vdots \\ B_k \in \uparrow_{R_i} A_k}} \text{wt}(A \rightarrow \sigma(B_1, \dots, B_k)) \sqsubseteq \sum_{\substack{B_1 \in \uparrow_{R_i} A_1 \\ \vdots \\ B_k \in \uparrow_{R_i} A_k}} \text{wt}(B \rightarrow \sigma(B_1, \dots, B_k))\}$$

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until $R_i = R_j$

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Every backward bisimulation [Högberg et al '07] is a backward simulation.

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If \preceq is the greatest backward simulation, then (G/\simeq) with $\simeq = \preceq \cap \preceq^{-1}$ is backward-simulation minimal.

(i.e., it cannot be reduced further via backward simulation)

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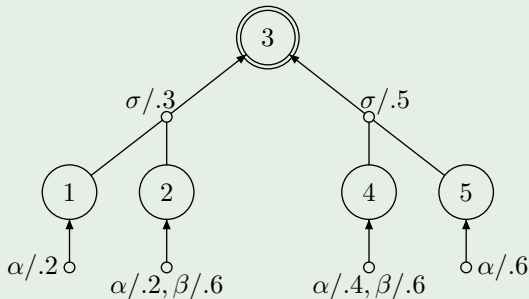
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no similar states

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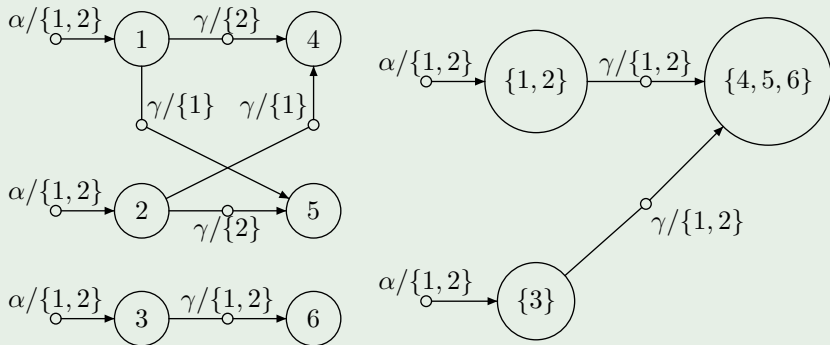
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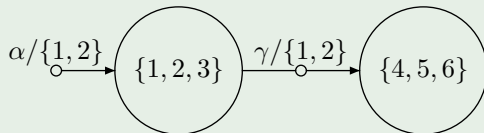
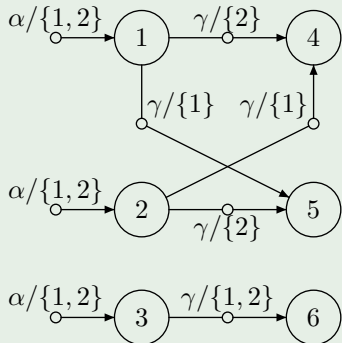


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- **MALETTI**
A backward and a forward simulation for weighted tree automata.
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